

Selected File: /opt/propice/propice-2.0/src/demo/truck-demo/propice/data/truck-demo.opf

Selected OP: |Move Valve|

Move Objects

Create Node

Create If Node

Open Node

Create Edge

Create Knot

Flip Conj/Disj In

Flip Conj/Disj Out

Edit Object

Duplicate Object

Merge Node

Convert End

Convert Start

Align Objects

Align Objects Vert

Align Objects Hor

Destroy Object

Relevant OP

Move Valve

INVOCATION:`<(! <POSITION VALVE $X>>`**CONTEXT:**`<(AND <ALARM YES>
<DELAY TWO-GOOD $DEL-2TBS>
<DELAY ONE-GOOD $DEL-1TB>>`**EFFECTS:**`<(<=> <POSITION VALVE $X>>>`**DOCUMENTATION:**

"This OP tries to put the valve in position \$x. It waits (\$del-2tbs) time units if the two sensors are good, or (\$del-1tb) time units if only one is good. After this time, it shutdowns if the trusted sensor(s) is not in good position."

